

The Chemical Basis of Morphogenesis

A.M. Turing, 1952

The paper discussed is by Alan Turing. It was published in 1952 and presents an idea of how periodic patterns could be formed in nature.

Looking on periodic structures – like the stripes on tigers, the dots on leopards or the whirly leaves on woodruff – it is hard to imagine those patterns are formed by pure chance. On the other hand, thinking of the unbelievable multitude of possible realizations, the patterns can not all be exactly encoded in the genes.

The paper “The Chemical Basis of Morphogenesis” proposes a possible mechanism due to an interaction of two “morphogenes” which react and diffuse through the tissue. Fulfilling some constraints regarding the diffusibilities and the behaviour of the reactions, this mechanism – called *Turing mechanism* – can lead to a pattern of concentrations defining the structure we see.

I. TURING MECHANISM

The central roll is played by two “morphogenes”. This term describes their function as a “form producer”. Morphogenes are not by them self the material that formates the pattern. They are for example enzymes and their concentrations influence the processes which are creating the pattern e.g. by stimulating or suppressing the production of pigments. The idea that *diffusion* is a driving force for the *formation* of patterns might not be that intuitive. In most cases, diffusion destroys patterns of concentration over time.

A picturesque example for pattern formation due to diffusion is the following: Consider random fire outbreaks in a dry forest. The expanding wildfires would then be one morphogene slowly diffusing. A second morphogene in the form of fire fighters diffuses *much faster* (e.g via airplanes) to the seats of fire and extinguishes it. An areal image of the forest would show a green area with a pattern of black patches.

The keys in this example are that:

1. One morphogene is *excitatory*, the other one is *inhibitory*.
2. The inhibitory morphogene diffuses faster the excitatory.

A. The Setting

The system of interest is for example an embryo in the early stage of the embryogenesis. The following setting will be used: There are two morphogenes whose concentrations are denoted c_1 and c_2 , they depend each on the two dimensional position x and the time t : $c_{1,2} = c_{1,2}(x, t)$. Those concentrations underlay in general the influence of the reactions f and g , respectively, and diffusion. The reactions depend on both concentrations each, so: $f = f(c_1, c_2)$ and $g = g(c_1, c_2)$. These functions can take positive and negative values, describing the creation and dismantling of morphogenes. The diffusion is described according to the usual diffusion function by $D_1 \nabla^2 c_1$ and analogue for the second morphogene. Altogether, the change over time is described as it follows:

$$\begin{aligned}\dot{c}_1 &= f(c_1, c_2) + D_1 \nabla^2 c_1 \\ \dot{c}_2 &= g(c_1, c_2) + D_2 \nabla^2 c_2\end{aligned}$$

what is known as a *Reaction-Diffusion System*.

A slightly different and less intuitive notation will be used:

$$\begin{aligned}\dot{u} &= \gamma f(u, v) + \nabla^2 u \\ \dot{v} &= \gamma g(u, v) + d \nabla^2 v,\end{aligned}\tag{1}$$

what is justified by making the calculations later more natural. In Eq. (1), c_1 is rescaled to u and c_2 to v . $\gamma = L^2/D_1 T$ represents the scaling factor with L the spatial, T the time scale. The diffusibilities are normalized with respect to D_1 and so the second equation get assigned the factor $d = D_2/D_1$.

B. Turing Mechanism

Obviously there is a multitude of solutions for this differential equations Eq. (1). But to be a *Turing mechanism* there are three conditions that must hold:

- (I) There is a homogeneous and stationary positive solution (u_0, v_0) for $f(u_0, v_0) = g(u_0, v_0) = 0$.
- (II) The System is stable if *no* diffusion occurs.
- (III) The System is unstable under diffusion.

These constraints limit the space of solutions to those describing systems where diffusion driven pattern formation is possible.

II. TURING ANALYSIS

The three conditions implicate constraints for both the reactions and the diffusion, which will be shown here. The process of checking for the above claims to hold is called *Turing analysis*.

a. First Condition To check if a homogeneous and stationary positive solution exists, determine the solution for $f(u_0, v_0) = g(u_0, v_0) = 0$. The existence of such a solution means that there is a pair of c_1, c_2 for which both reactions neither produce, nor destroy either of the morphogenes. Since negative concentration make no sense, the solution must be positive.

b. Second Condition The second condition requires, that the system has to be stable if the diffusion is suppressed. The Reaction-Diffusion system Eq. (1) therefore misses the diffusion term, and reads:

$$\begin{aligned}\dot{u} &= \gamma f(u, v) \\ \dot{v} &= \gamma g(u, v).\end{aligned}$$

This should be stable under a small perturbation around the stable state (u_0, v_0) , which is the solution from the first condition.

The perturbed stable states are written as

$$w = \begin{pmatrix} u - u_0 \\ v - v_0 \end{pmatrix}.$$

As the system can be considered as linear, w behaves like $w \propto e^{\lambda t}$.

With the shorthand $f_u = \partial f / \partial u$ the Jacobian matrix reads:

$$A = \begin{pmatrix} f_u & f_v \\ g_u & g_v \end{pmatrix}.$$

It follows, that at the stable state (u_0, v_0) the linear behaviour yields:

$$\dot{w} = \gamma A w.$$

Since the System has to be stable under this perturbation for the condition to hold, the eigenvalues $\lambda_{1,2}$ solving $\det(\gamma A - \lambda \mathbb{1}) = 0$ have to be negative.

The eigenvalues are given by:

$$\lambda_{1,2} = \frac{1}{2} \gamma \left[(f_u + g_v) \pm \sqrt{(f_u + g_v)^2 - 4(f_u g_v - f_v g_u)} \right]. \quad (2)$$

For the real part of $\lambda_{1,2}$ to be negative, the term in front of the square root must be negative and the last one in the square root positive. So the requirement of the state to be stable with no diffusion present implies conditions on the derivatives of the functions describing the reactions:

$$f_u + g_v < 0 \quad (3)$$

$$f_u g_v - f_v g_u > 0. \quad (4)$$

Thus this condition gives constraints to how the behaviour of the reactions change with respect to a change in the concentrations.

c. Third Condition The last condition demands, that the system becomes unstable, as the diffusion is again considered. For this the diffusion term from Eq. (1) has to be taken into account. In the now used notation and with the diffusion, linearized dynamics reads:

$$\dot{w} = \gamma A w + D \nabla^2 w, \quad (5)$$

with the matrix D containing the information about the diffusibilities:

$$D = \begin{pmatrix} 1 & 0 \\ 0 & D_1 \end{pmatrix}.$$

As discussed before, the concentrations depend on both, space and time, hence $w = w(x, t)$. A separation ansatz is used to disentangle the two dependencies:

$$w(x, t) = \sum_k c_k e^{\lambda_k t} W_k(x). \quad (6)$$

The respective state of the two concentrations at the location x and the time t is expressed as a series of modes. Each mode k separates in a spacial eigenfunction $W(x)$ and the ‘‘time development’’ $e^{\lambda_k t}$ of the starting state c_k .

Still considering linear behaviour of $w(x, t)$ under a small perturbation, Eq. (5) yields for a mode k

$$\lambda(k) W_k = \gamma A W_k + D \nabla^2 W_k. \quad (7)$$

This expression describes the k 'th mode (with k is the wave number $k \propto 1/\lambda$), note that the notation is not perfectly ‘‘clean’’ in a mathematical sense, since k is used ambiguous as a index and a parameter. This is justified by its physical meaning.

In order to get rid of the second derivative in the diffusion term, the solution of the spacial eigenvalue problem is used:

$$\nabla^2 W(x) + k^2 W(x) = 0.$$

This allows to replace ∇^2 by $-k^2$ in Eq. (7):

$$\begin{aligned}\lambda(k) W_k &= \gamma A W_k + D \nabla^2 W_k \\ &= \gamma A W_k - D k^2 W_k.\end{aligned}$$

Since the system should be unstable now, the resulting real parts of the eigenvalues $\lambda_{1,2}$ from $\det(\lambda \mathbb{1} - \gamma A + D k^2) = 0$ must be positive. The eigenvalue equation reads:

$$0 = \lambda^2 + \lambda [k^2(1+d) - \gamma(f_u + g_v)] + h(k^2).$$

With the last term short for

$$h(k^2) = d k^4 - \gamma(d f_u + g_v) k^2 + \gamma |A|.$$

The system is unstable when $Re(\lambda(k)) > 0$, that means that either:

- $[k^2(1+d) - \gamma(f_u + g_v)] < 0$
- $h(k^2) < 0$

The first expression can not be true, since the diffusion must be positive and therefore $d > 0$, and $f_u + g_v < 0$ is a result from Eq. (3).

Thus, for the system to be unstable it must hold that

$$h(k^2) = d k^4 - \gamma(d f_u + g_v) k^2 + \gamma |A| < 0. \quad (8)$$

Because all other values contribute positive, for $h(k^2) < 0$ it must hold that $(d f_u + g_v) > 0$.

So, at the same time it has to hold, that $(d f_u + g_v) > 0$ and $(f_u + g_v) < 0$ (known from Eq. (3)). That leads to some implications:

- f_u and g_v have different signs. The morphogene u typically acts autocatalytic, therefore $f_u > 0$, $g_v > 0$.
- The sum changes the sign as d is applied to f_u . That means, that $D_2/D_1 > 1$. So the inhibitory morphogene diffuses faster than the excitatory, which was used in the illustration above.

While being a necessary criterion, $(df_u + g_v) > 0$ by itself is not sufficient. For the third condition to hold true in total, Eq. (8) must be fulfilled. For this $h(k^2)$ (and k^2 , respectively) is evaluated at the minimum:

$$h_{min} = \gamma^2 \left[|A| - \frac{(df_u + g_v)^2}{4d} \right], \quad k_{min}^2 = \gamma \frac{(df_u + g_v)}{2d} \quad (9)$$

it holds, that $h(k^2) < 0$ for:

$$\frac{(df_u + g_v)^2}{4d} > |A|. \quad (10)$$

III. PATTERN FORMATION

If all the constraints to the space of possible solutions are fulfilled, it is possible for a pattern to be formed. That means there is a critical value d_c for which smaller values do not fulfill the third condition:

$$|A| = \frac{(d_c f_u + g_v)^2}{4d_c}.$$

The meaning of this can be made clear by once again using the image from above. For a wildfire resulting in a pattern of burned forest the difference in the diffusibilities is a key. If the firefighters are too fast, the fire would not have the necessary time to burn a patch down. If they are too slow, all the forest would have burned down, and again no pattern would appear in the end.

In this model, with Eq. (9), the existence of a d_c implies, that there is a k_c for that:

$$k_c^2 = \gamma \frac{d_c f_u + g_v}{2d_c} = \gamma \sqrt{\frac{|A|}{d_c}}.$$

Depending on the value for d , there is a single k (in this case: $k = k_c$), a range of k values or no k , for that patterns are possible:

- For $d > d_c$: roots at k_1, k_2 , instable for $k \in [k_1, k_2]$
- For $d = d_c$: root at k_c , instable for k_c
- $k \notin [k_1, k_2]$: no k value to fulfil the third condition, therefore no pattern.

As shown in Fig. 1, any case there are some small and large k , for that no patterns are possible.

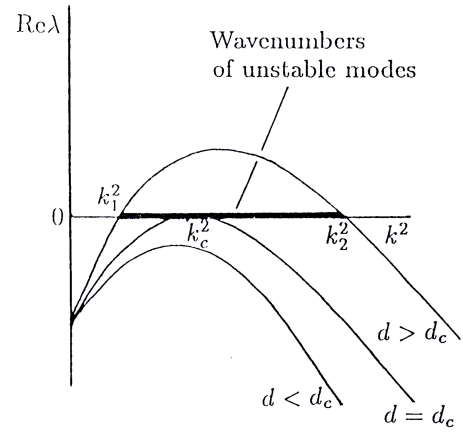


FIG. 1. Visualization of the range of k for which patterns can occur. source: J.D. Murray, Mathematical Biology II: Spatial Models and Biomedical Applications

An example for no pattern for large k would be a carpet for that black and white yarn alternate in so narrow distances, that it appears grey. Analogue, if the frequency is too low (small k) there would not be any change of color at all.

All in all, the three conditions lead to constraints to the forms of $f(u, v)$ and $g(u, v)$:

The need for stability while suppressing the diffusion gives:

$$\begin{aligned} f_u + g_v &< 0 \\ f_u g_v - f_v g_u &> 0. \end{aligned}$$

While the instability under spatial perturbation yields:

$$\begin{aligned} df_u + g_v &> 0 \\ (df_u + g_v)^2 &> 4d|A|. \end{aligned}$$

A. Visualisation

The impact of the spacial aspect on the pattern formation can be shown by simulating different sizes by changing the scale parameter γ in Eq. (1):

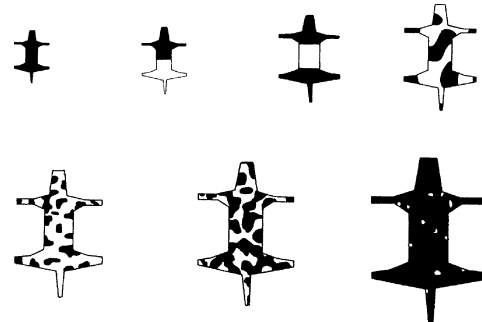


FIG. 2. Simulation of different fur sizes. source: J.D. Murray, Mathematical Biology II: Spatial Models and Biomedical Applications

As seen in Fig. 2 this mechanism does not lead to pattern formation for both cases of very small (e.g. a mouse) or very

large (elephant for example) fur sizes. This prediction is fulfilled by the majority of animals with the respective size. It has to be noted tho, that the here discussed mechanism of pattern formation is not the only one in nature (but the only diffusion driven). The reason why there are no pattern for too small fur sizes is straight forward. The spacial constraint restricts the possible wave modes to a region close to $k = 0$ and so suppresses pattern formation. As the size gets bigger pattern begin to appear. First with low frequency as seen in goats and sheeps for example, than more complex like on chetha, leopards and so on. The upper end of the scale appears again unicolored. The reason here is, that the frequency is to high and the dominant wave modes tend to $k \rightarrow \infty$. There are some comparisons between the simulation and real patterns. For example in Fig. 3 for different species of giraffe:

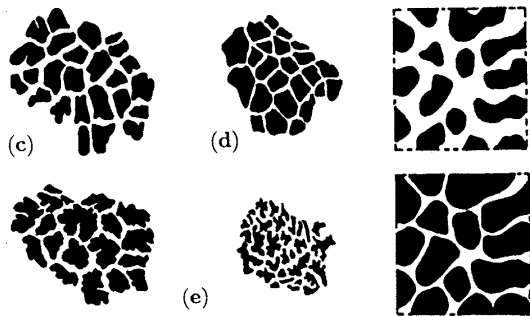


FIG. 3. Comparison between simulated (right) and real (left and middle) patterns of different giraffe species.

source: J.D. Murray, *Mathematical Biology II: Spatial Models and Biomedical Applications*

An interesting effect can be seen at Fig. 4. Thinking of the fur as a two dimensional surface, the dots on chethas represent the overlap of weaves in different dimensions. The tail can then be seen as effective reduction to one dimension. If the x axis is defined along the tail, the expansion in y underlays the same condition and effect as for small fur sizes in general, but the suppression of pattern only effects one dimension, so the dots transform to stripes.

This is the reason, why spotted animals can have striped tails but not vice versa. The latter would imply, that in the tail waves from the y direction appear that are not there in the main area of the fur.

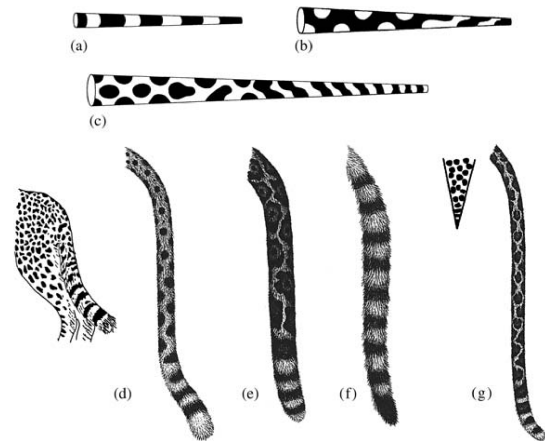


FIG. 4. Comparison between simulated (above) and real (below) tails of different cheetha species.

source: J.D. Murray, *Mathematical Biology II: Spatial Models and Biomedical Applications*

IV. SUMMARY

In the early stages of the embryogenesis, the embryo can be considered as homogeneous tissue. In this phase the reaction and diffusion does not depend on the spatial parameter. The mechanism of pattern formation proposed by Alan Turing describes a set of conditions, under which pattern can be formed in this stage. The whole process bases of the assumption of linear behaviour under small perturbations in the spacial distribution of the concentrations, like they are usual due to thermal influences for example. In the limit of large times, this assumption will lose its legitimacy eventually. At this point in the embryogenesis the process will ultimately halt. The current distribution of concentration will be “frozen” so to say. Since the concentrations are those of morphogenes there will be a visual pattern following the pattern of concentrations. This process gives an elegant possibility of how the unbelievable diversity of different expressions can be coded. The specific morphogenes in action with their specific diffusibilities and reactions determine the length scale The concrete expression however is exposed to random effects.

V. LITERATUR

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